

Cryogen-free cryostat with sample changer for fast automatic data collection

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MLZ is a cooperation between:

Compact Cryostat – Current topics

1. Thermally decoupling of sample holder

⇒ Leakages whilst testing

2. Thermal connection of sample

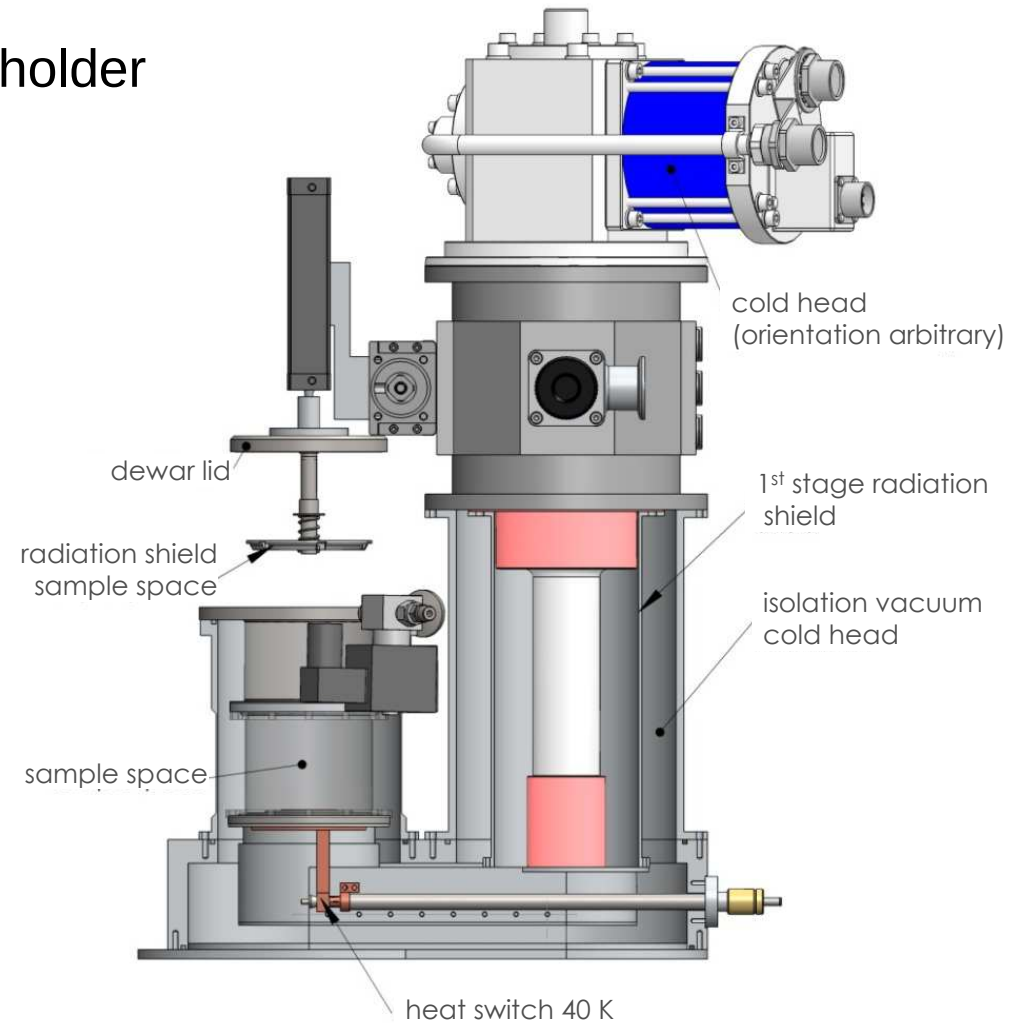
⇒ Research at other institutes

⇒ Concepts

3. Icing inside the sample tube

⇒ Sample tube heating

⇒ Gas flow improvement



1st topic

Thermally decoupling of sample desk

Thermal decoupling - Sample desk

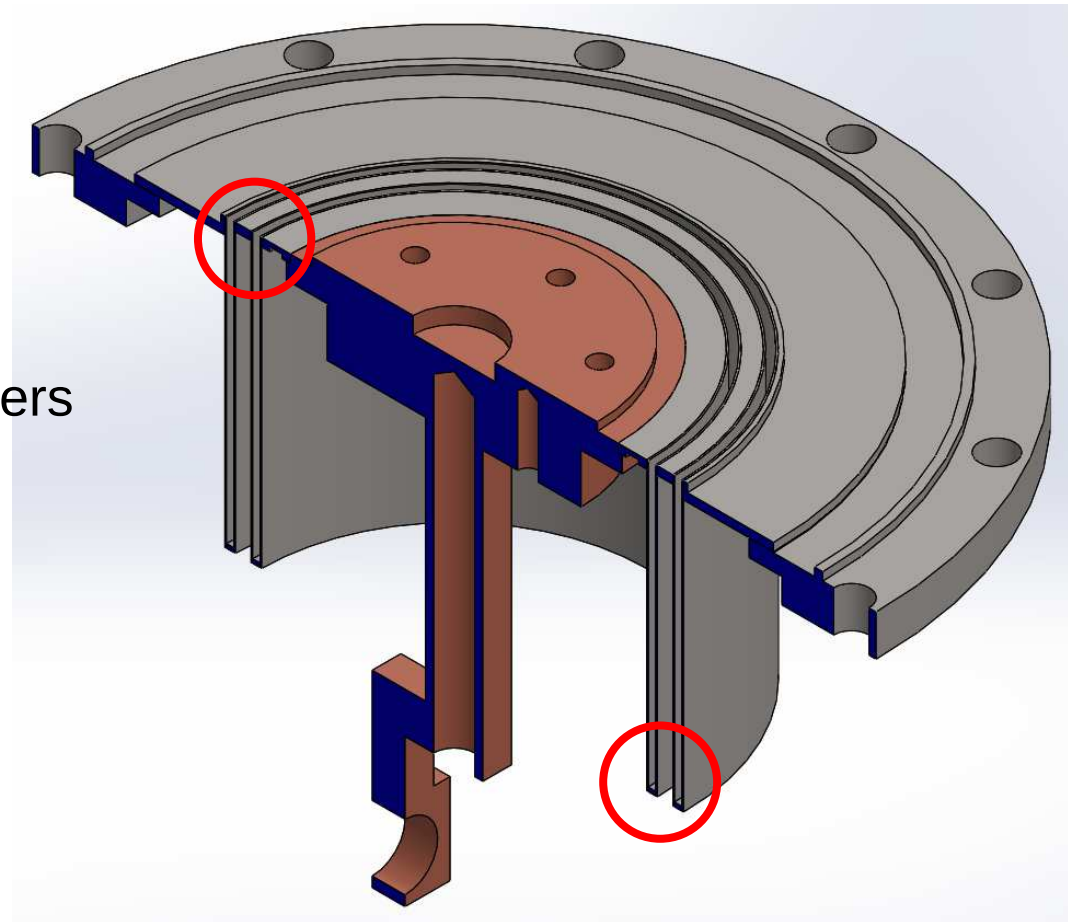
Problem:

Structure too filigree

⇒ New leakages whilst handling

New concept:

- Larger distance between cylinders
- Soldering at the cylinders



2nd topic

Thermal connection of sample → Research

Commercially available robots and sample exchange systems

Bruker (BruNo)

-Robot for X-ray crystallography

MarXperts (MARCSC)

-Automated sample changing robot for X-ray crystallography integrated in the marXperts multi-purpose goniometer

IRELEC (CATS)

-Complete sample exchange system using “Stäubli”-robot

NatX-ray (G-Rob)

-Robot-based system for crystallography (derived from CATS)

Existing automated sample changer at facilities

BCSB [BCSB Wiki]

Berkeley Lab – Advanced Light Source [Snell et al. 2004]

EMBL Grenoble Outstation (SC3) [Cipriani et al. 2006]

EMBL Hamburg Outstation [Pohl et al. 2004]

ESRF (upgraded *CATS*) [Jacquamet et al. 2009], [Fitch 2014]

J-PARC (*iMATERIA*) [Hoshikawa et al. 2010, 2014]

Max Planck Research Unit for Structural Molecular Biology [Karain et al. 2002]

Oxford Instruments Omicron NanoScience [Batey et al. 2014]

Rigaku in collaboration with Abbot Laboratories (*ACTOR*) [Muchmore et al. 2000]

SNS (FERNS and PAC) [Heroux 2014], [Rix et al. 2007], [Wenzel]

SPRING-8 (*SPACE*) [Ueno et al. 2004], [Murakami et al. 2012]

SSRL (*SAM*) [Cohen et al. 2002, 2005]

Structural Biology Research Centre at the Photon Factory (*PAM*) [Hiraki et al. 2012/2013, 2013]

2nd topic

Thermal connection of sample → Concepts

Possible direct thermal connections

Screwing	→	Rotatory and/or vertical strain
Plugging / Bayonet	→	Vertical strains
Magnetic	→	Induction
Under pressure	→	Limited space, sealing
Clamping	→	Space? → Piezo actuators

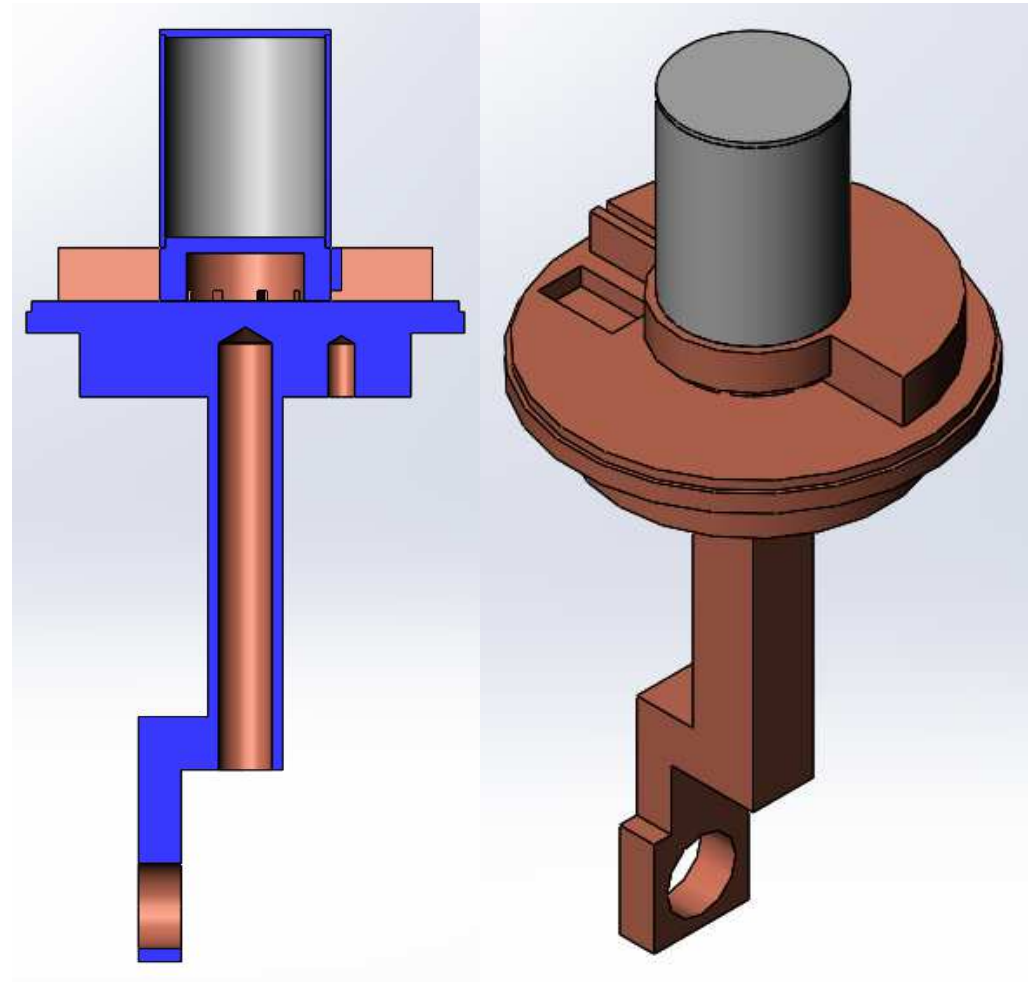
Thermal connection

Sample holder:

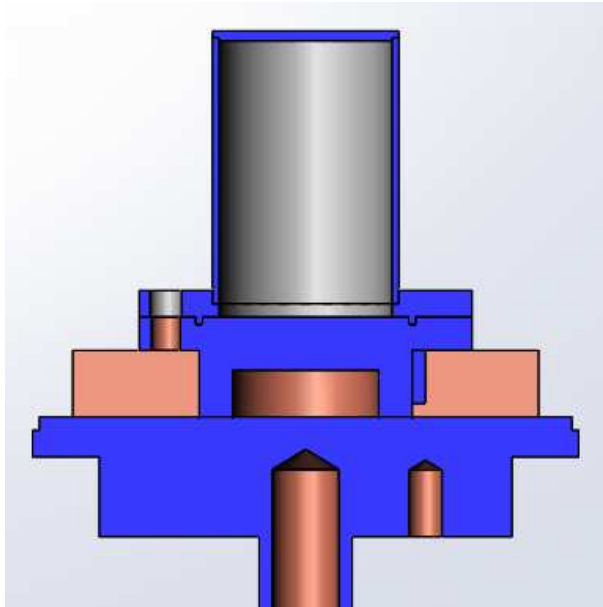
- Copper base
- Deep drawn container

Clamping mechanism:

- Copper spring incorporated into sample desk
- Driven by piezo actuator

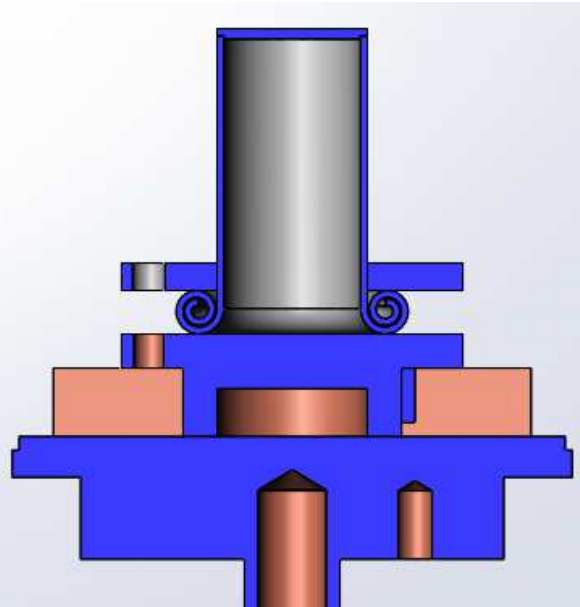


Sample holder sealing



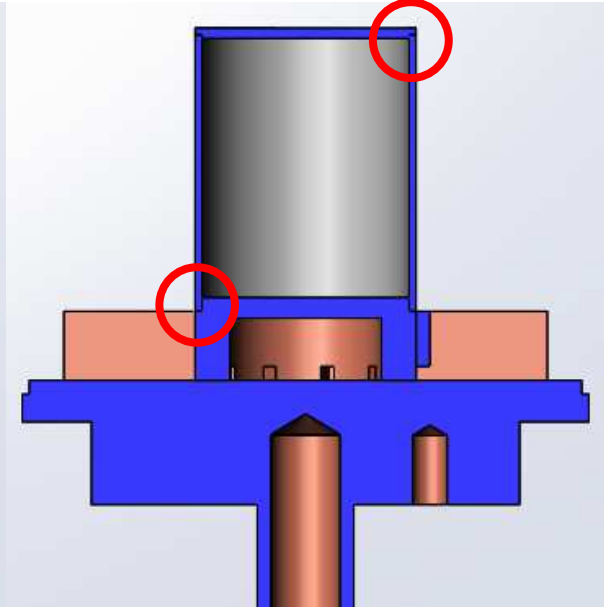
Indium

- Detachable
- Easy sample attachment
- Can loosen at low Temperatures



Spring

- Detachable
- Easy sample attachment
- No experiences yet



Orbital welding

- Permanent connection
- Small size ratio
- Two welding seams necessary

3rd topic

Icing inside the sample tube

Sample tube heating

Thermal decoupling between
sample desk and sample tube
„too good“

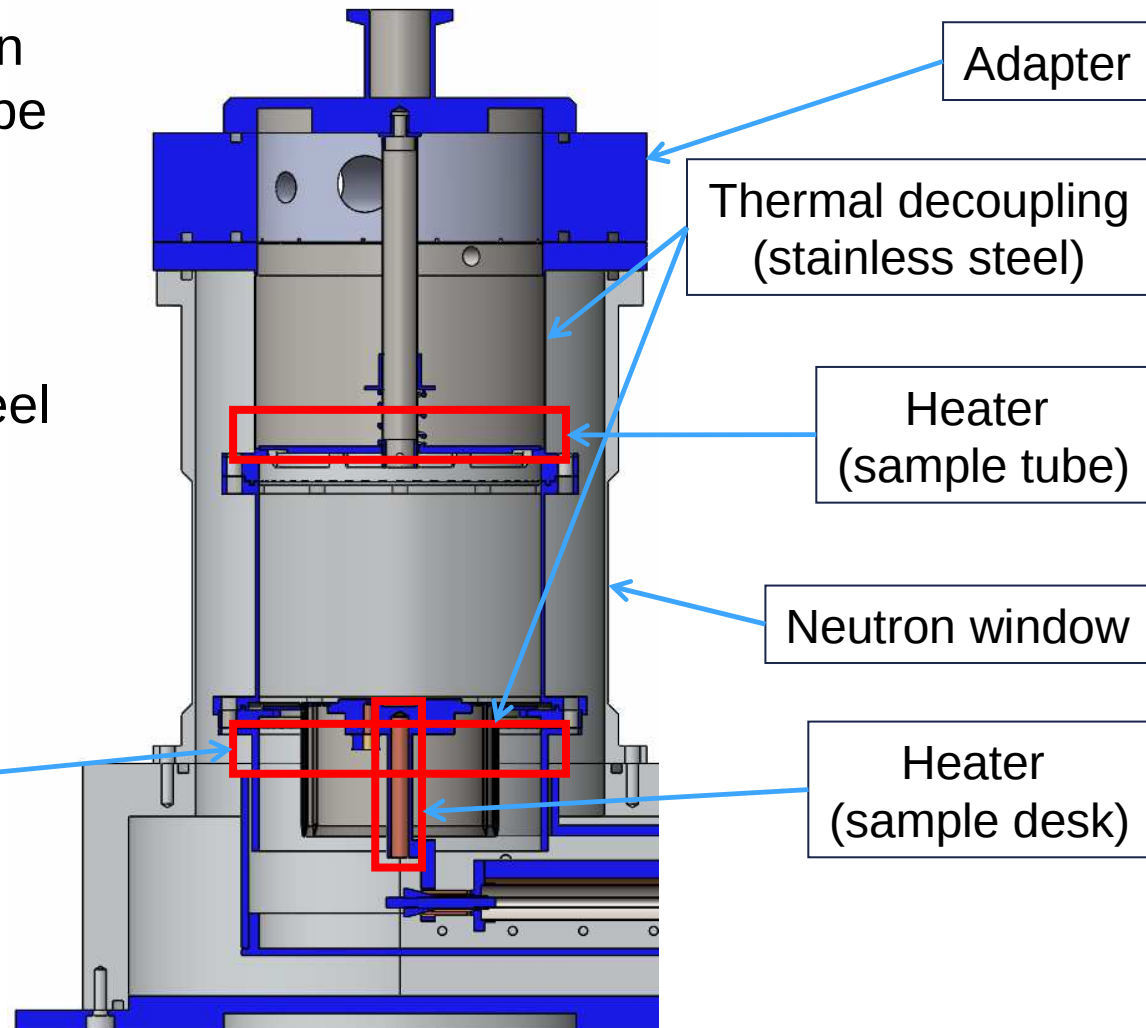
⇒ Tube stays cold

Heater collar at stainless steel
part

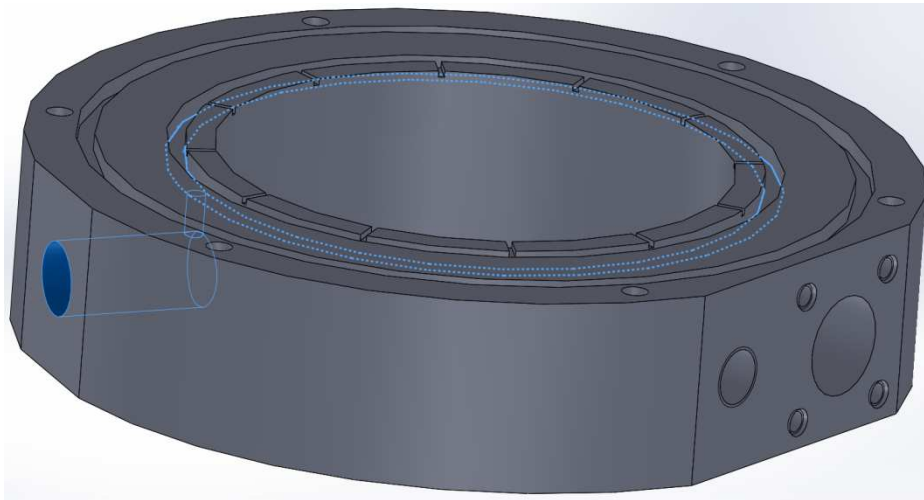
⇒ No icing in heater region

⇒ Above and below still icing

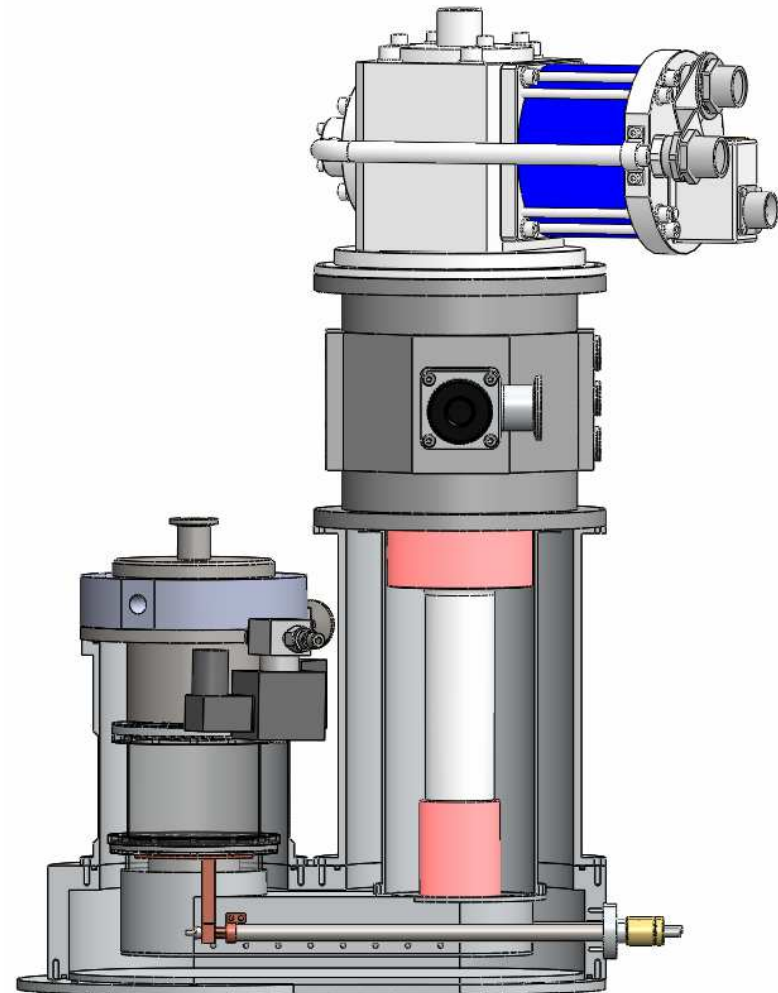
⇒ Relocation of heater
necessary



Gas flow distribution



Gas inflow all around the sample tube
 ⇒ Less fog inside the sample tube
 ⇒ After a short time still icing inside the sample tube



Thank you for your attention!



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